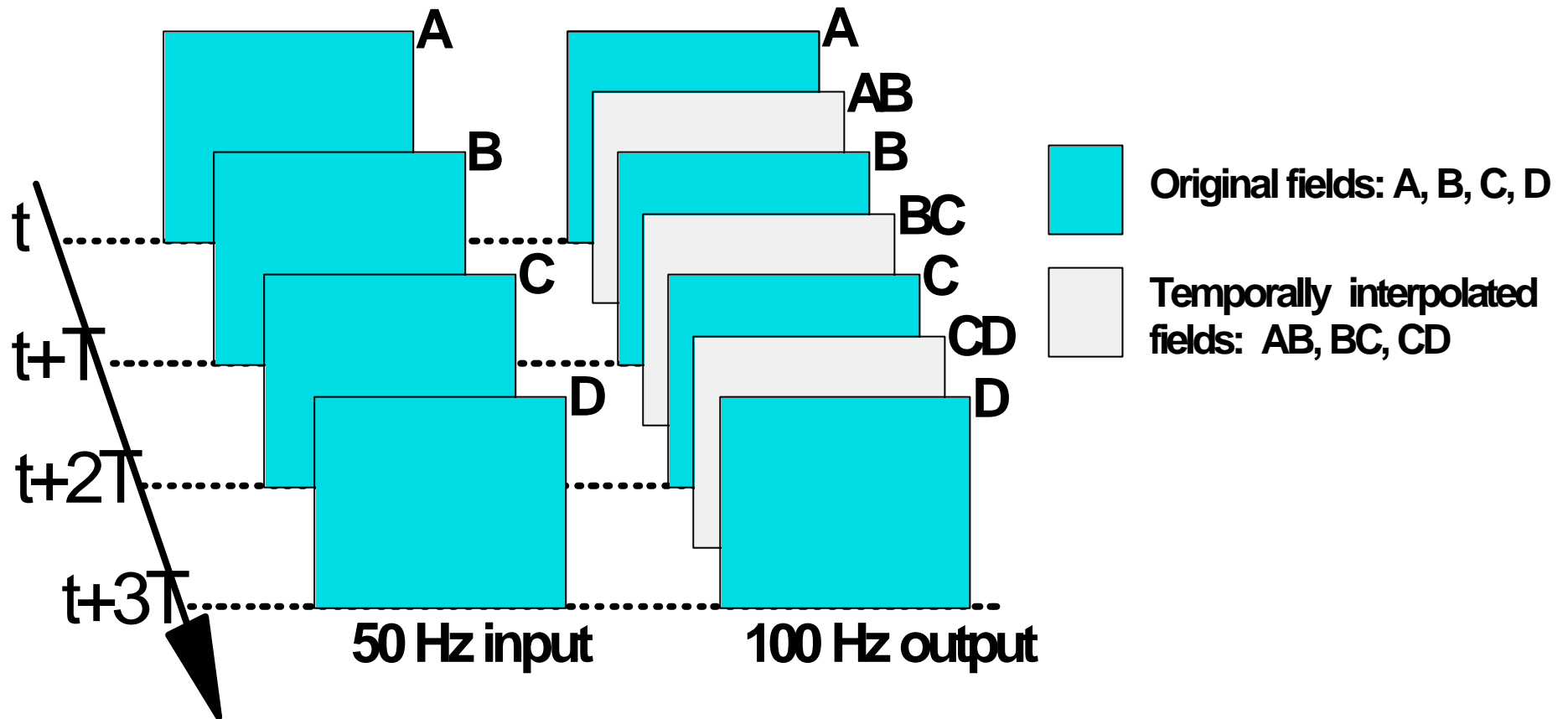


# Scan rate conversion

**Field Rate Doubling (FRD) and  
Line Rate Doubling (LRD or de-interlacing)**

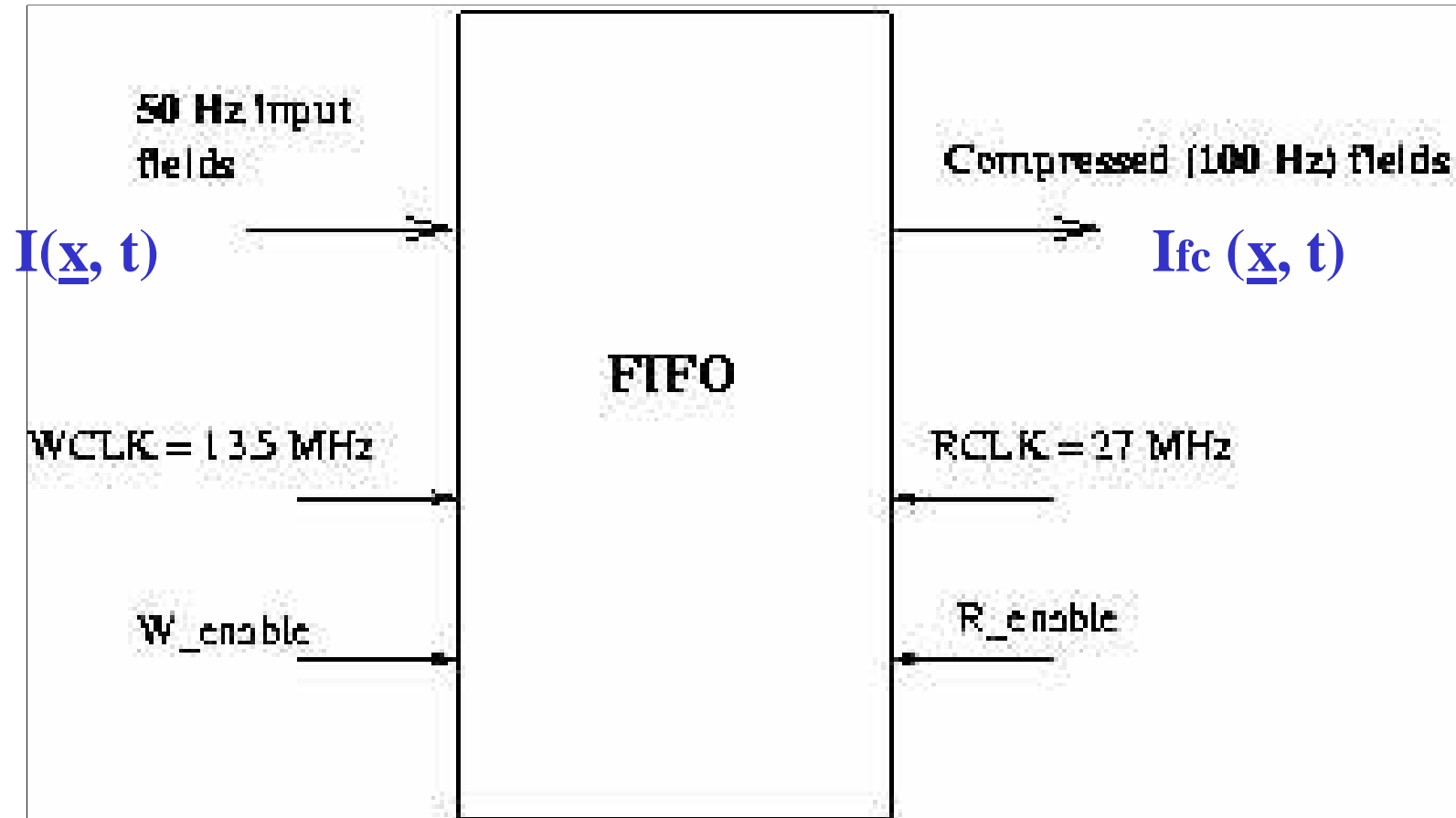


# Field Rate Doubling



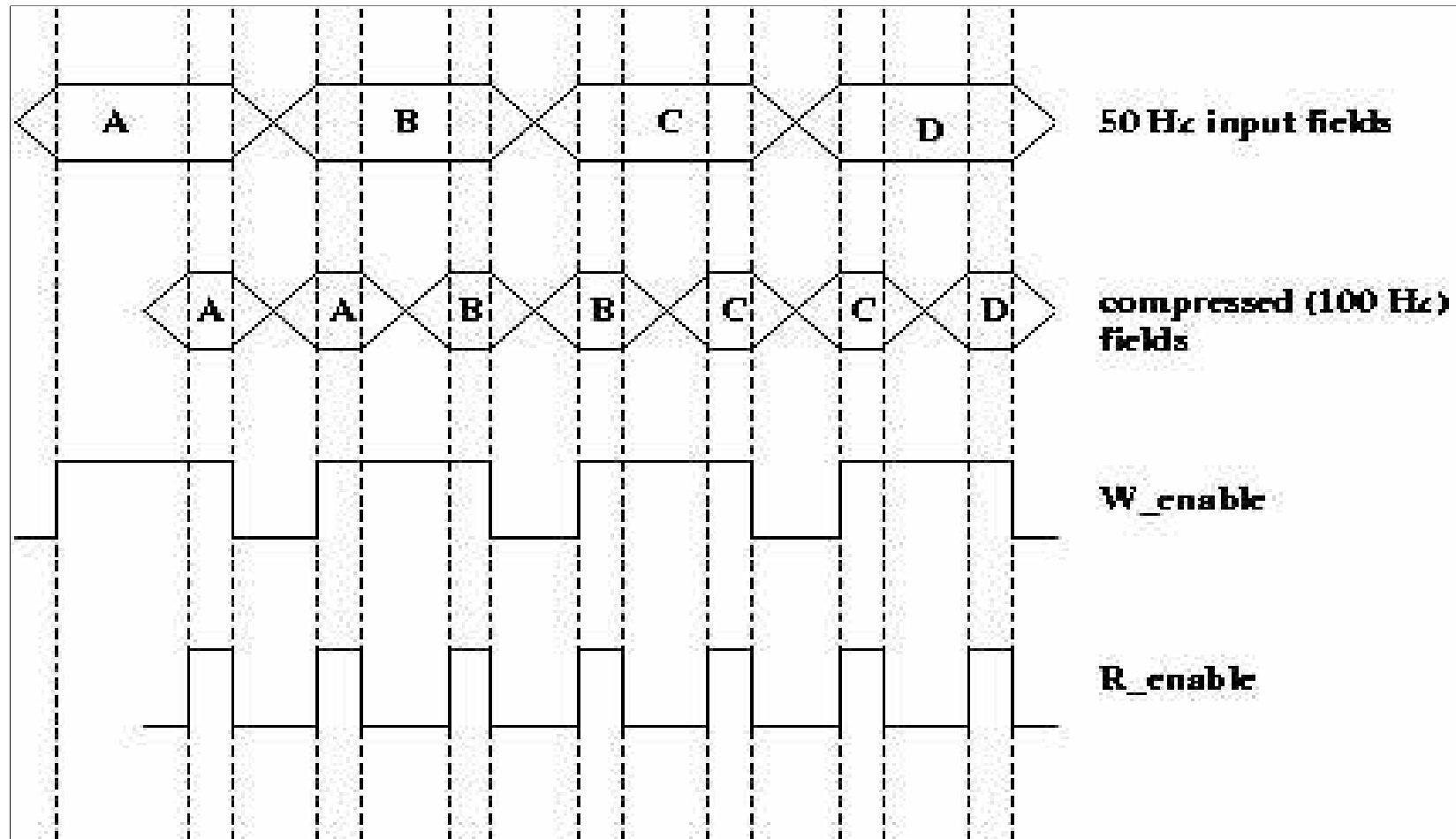
Two 100 Hz output fields are generated for each 50 Hz input field.

# Time Compression (1)



**A field memory device, with asynchronous write (WCLK) and read (RCLK) clocks, obtains the time compression.**

# Time Compression (2)

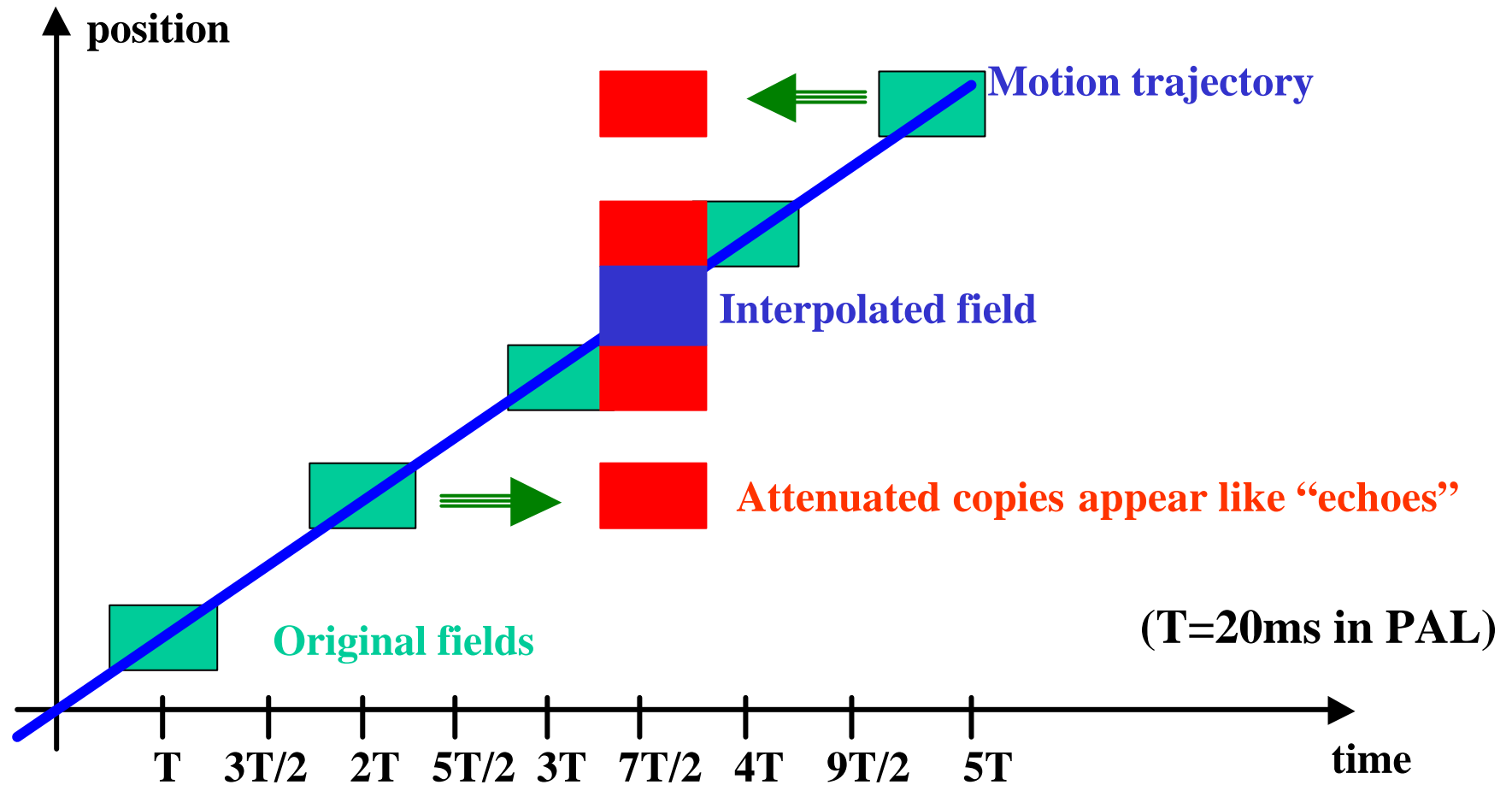


The processor works at two times the data rate. A theoretical time delay of  $0.5 T$  is introduced by the time compression.

# Disadvantages of classical SRC (1)

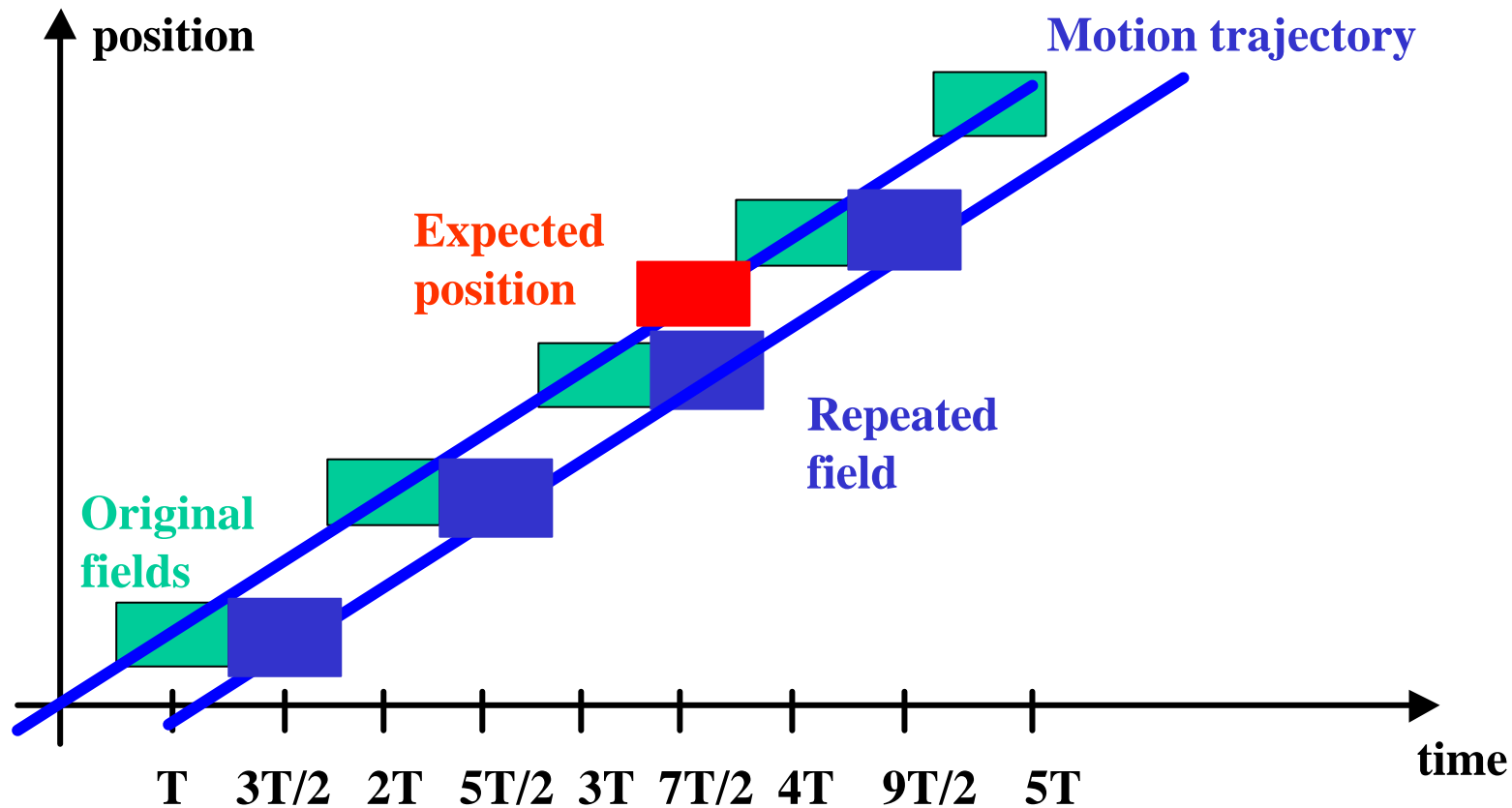
- **SRC temporal bandwidth limitation is unfeasible:**
  - A picture with moving texture or edges, causes non zero temporal frequencies on the screen.
  - However, on the retina of the observer who tracks the moving object, the temporal frequencies are zero.
  - If now high temporal frequencies caused by the object movement were removed from video signal, then the object would seem blurred for the observer.
- **The perception bandwidth of the eye for temporal frequencies does not apply to temporal frequencies in the video signal.**

# Disadvantages of classical SRC (2)



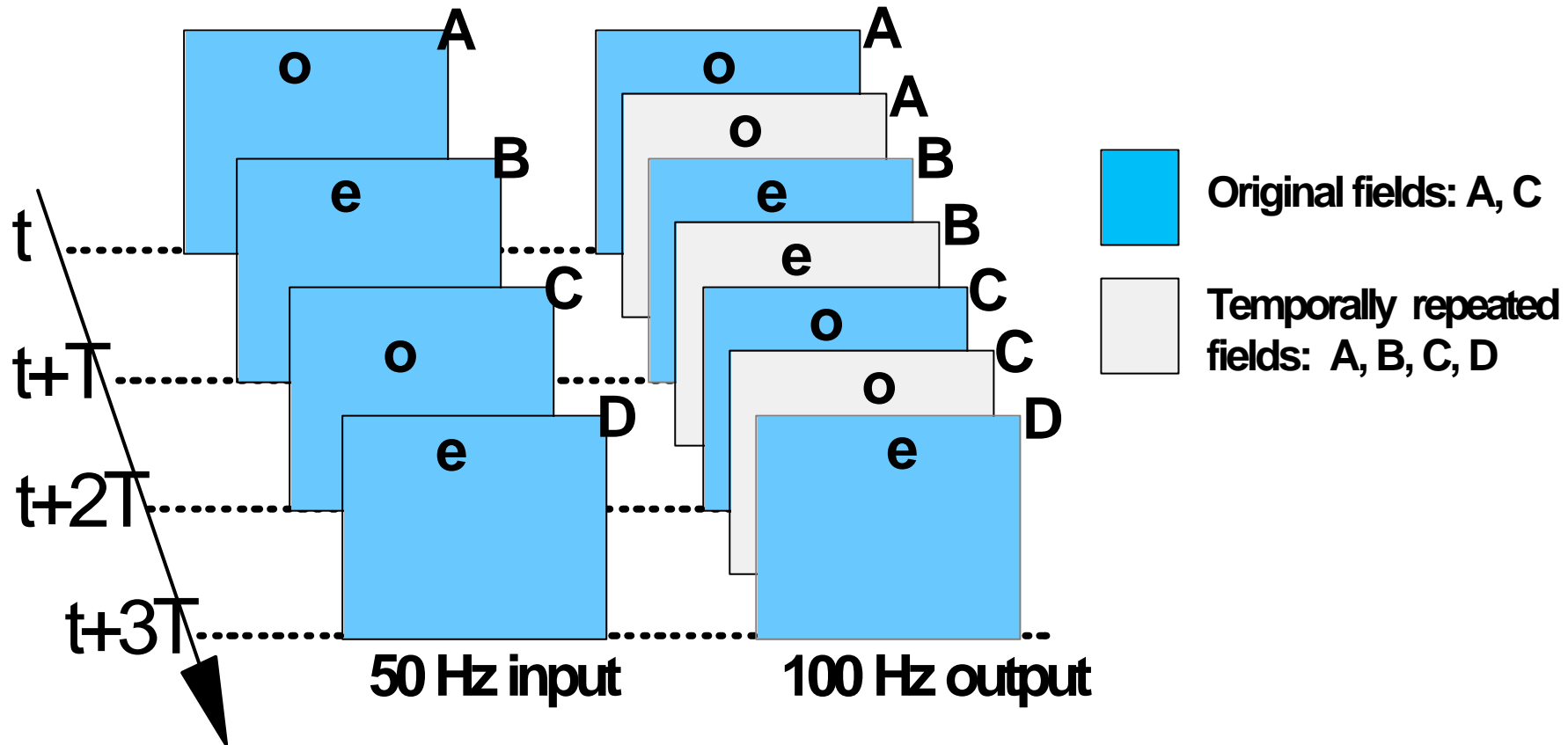
Temporal interpolation for an object tracking observer

# Field repetition (1)



output fields at  $t = nT$ :  $I_{out}(\underline{x}, t) = I_{fc}(\underline{x}, t)$  for  $t \% T = 0$ .  
 output fields at  $t = (n + 1/2)T$ :  $I_{out}(\underline{x}, t) = I_{fc}(\underline{x}, t - T/2)$  for  $t \% T = T/2$ .

# Field repetition (2)



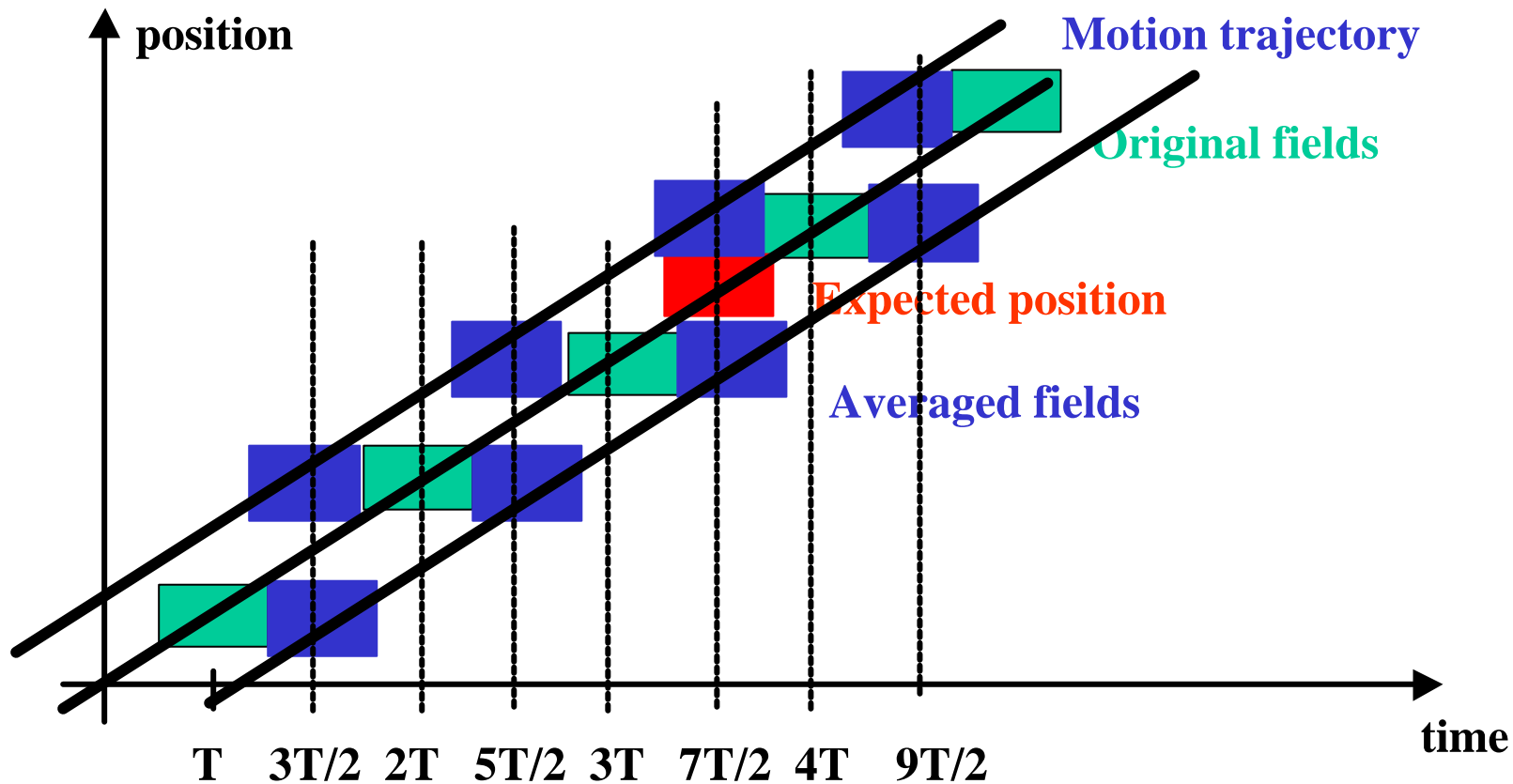
In a DSP fashion:  $I_{out}(n) = 1/2 [ I_{fc}(n) + I_{fc}(n-1) ]$  at  $t=n(T/2)$ . By Z transf.  $|H(z)| = | \cos(p f_t T) |$  with  $f_t$  temporal freq on the screen.



# Field repetition (3)

- **For the object tracking viewer, Field repetition gives rise to visible artifacts: low speeds introduce a blur, high speeds generate double images.**
- **The output sequence is OOEE rather than OEEOE required for correct interlacing output fields.**
  - **The problem is tackled by adapting the display deflection.**
- **Field repetition cannot solve the line-flickering, since every line is scanned two times (and so the line period is 64  $\mu$ s instead of 32 $\mu$ s of 100 Hz SD-TV).**

# Field averaging (1)



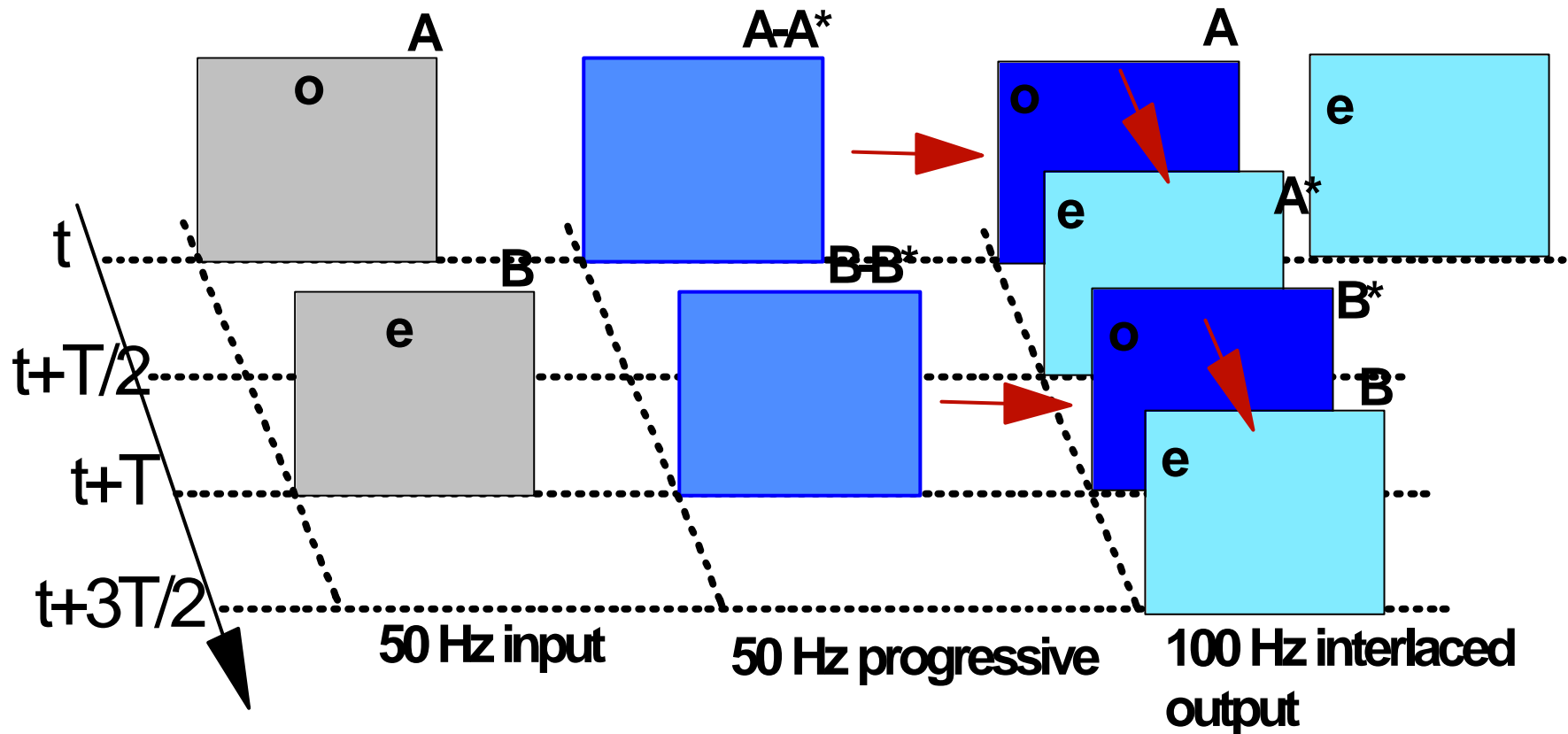
**Odd fields:**  $I_{out}(\underline{x}, t) = I_{fc}(\underline{x}, t)$  if  $t \% T = 0$ .

**Even fields:**  $I_{out}(\underline{x}, t) = 1/2 [I_{fc}(\underline{x}, t - T/2) + I_{fc}(\underline{x}, t + T/2)]$  if  $t \% T = T/2$ .

# Field averaging (2)

- **If the viewer tracks the motion, he perceives more blur than what is obtained with Field repetition.**
- **This method can have advantages for the legibility of moving text:**
  - **No single echoes occur in case of motion, but two echoes symmetrically about the lettering and with a 50% lower intensity.**
- **Field averaging can satisfactory be used in critical stationary image parts.**

# Philips “Digital Scan” 100 Hz (1)



# Philips “Digital Scan” 100 Hz (2)

- **Field 1 (  $t \% (2T) = 0$  ) :**

–  $I_{out}(\underline{x}, t) = I_{fc}(\underline{x}, t)$ .

$$I_{fc}(\underline{x} + \underline{(0,-1)}, t - T/2)$$

$$I_{fc}(\underline{x} + \underline{(0,+1)}, t - T/2) \quad I_{fc}(\underline{x}, t + T/2)$$

- **Field 2 (  $t \% (T/2) = 0$  ) :**

–  $I_{out}(\underline{x}, t) = \text{median}[ \quad I_{fc}(\underline{x}, t + T/2) , I_{fc}(\underline{x} + \underline{(0,-1)}, t - T/2) , I_{fc}(\underline{x} + \underline{(0,+1)}, t - T/2) \quad ]$ .

- **Field 3 (  $t \% T = 0$  ) :**

–  $I_{out}(\underline{x}, t) = \text{median}[ \quad I_{fc}(\underline{x}, t - T) , I_{fc}(\underline{x} + \underline{(0,-1)}, t) , I_{fc}(\underline{x} + \underline{(0,+1)}, t) \quad ]$ .

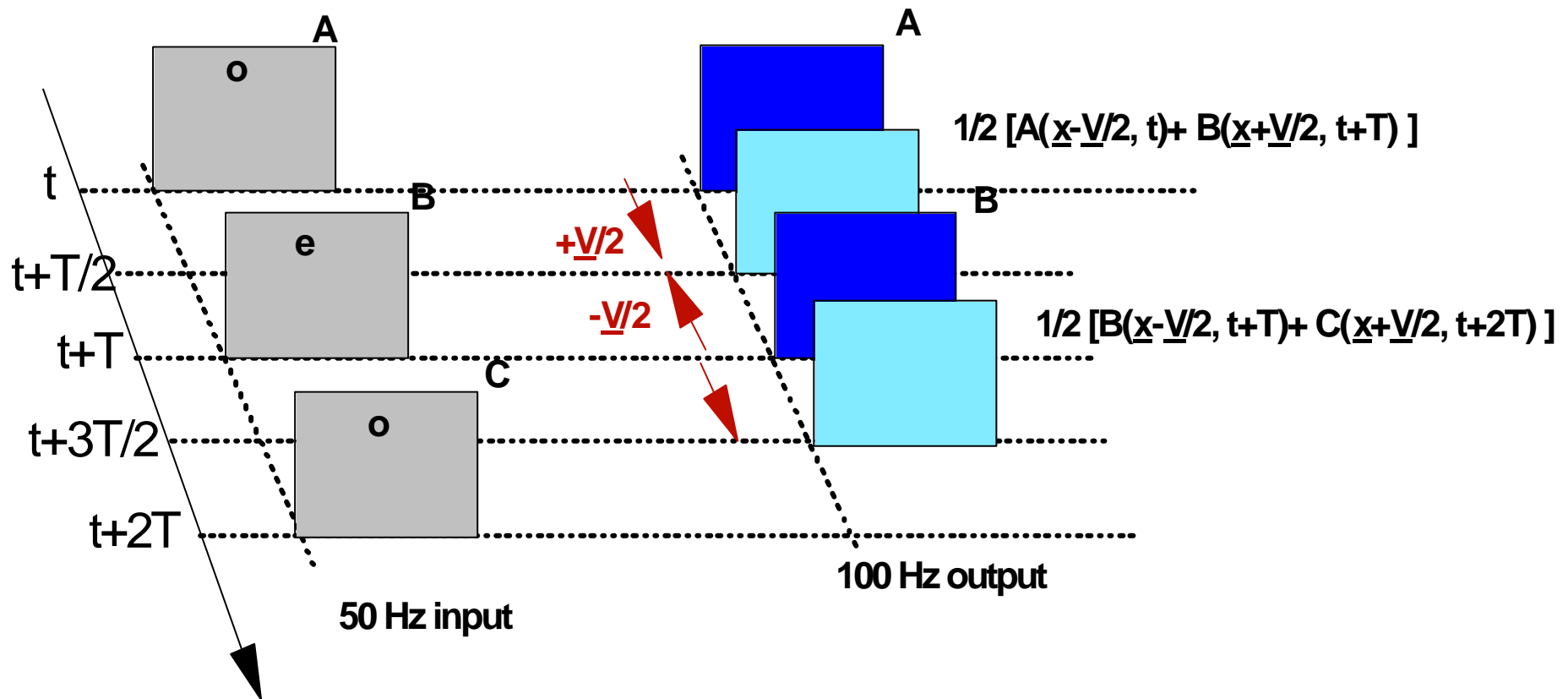
- **Field 4 (  $t \% (3T/2) = 0$  ) :**

–  $I_{out}(\underline{x}, t) = I_{fc}(\underline{x}, t - T/2)$ .

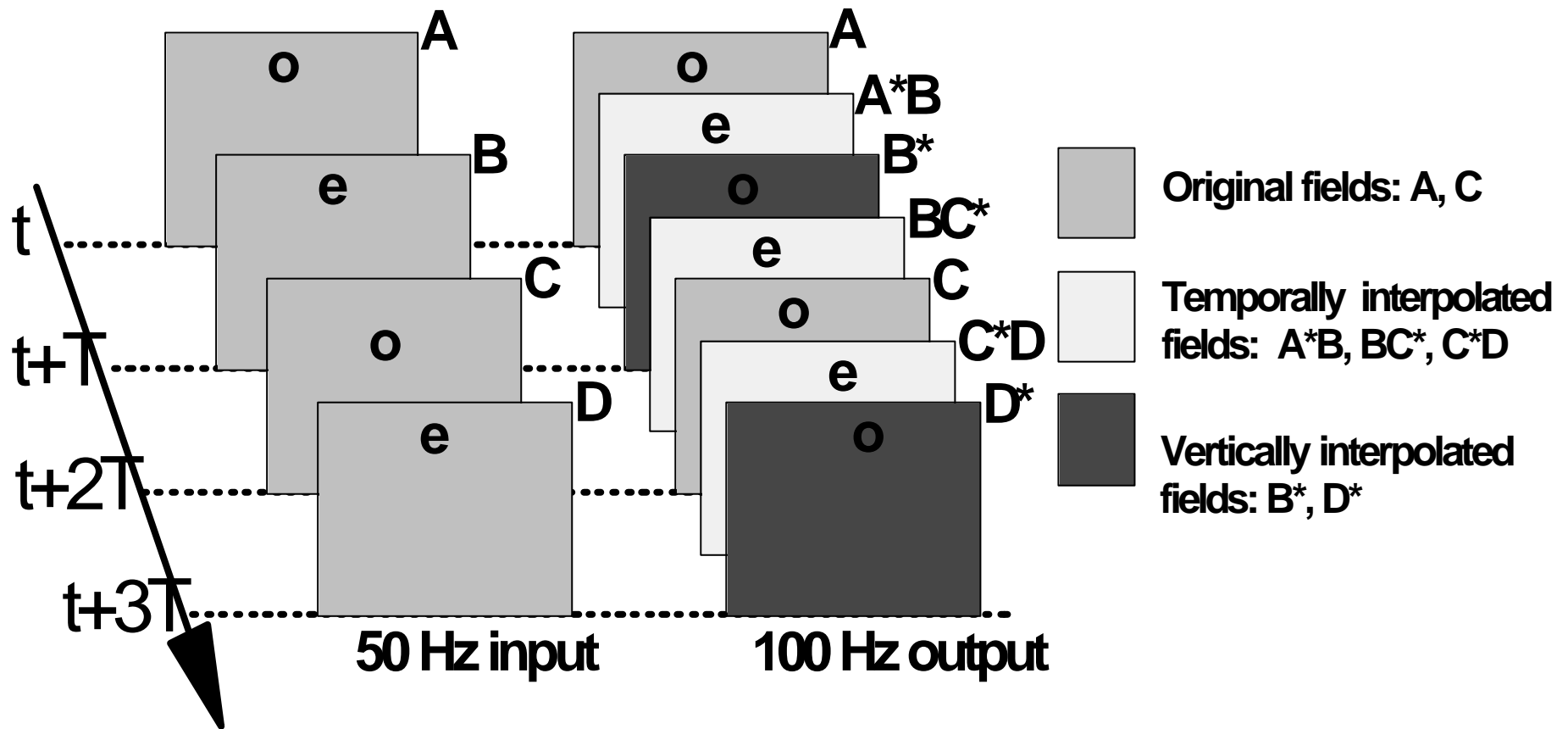
$$I_{fc}(\underline{x}, t - T) \quad I_{fc}(\underline{x} + \underline{(0,-1)}, t)$$

$$I_{fc}(\underline{x} + \underline{(0,+1)}, t)$$

# Motion Compensated field averaging



# Philips “Natural Motion” 100 Hz

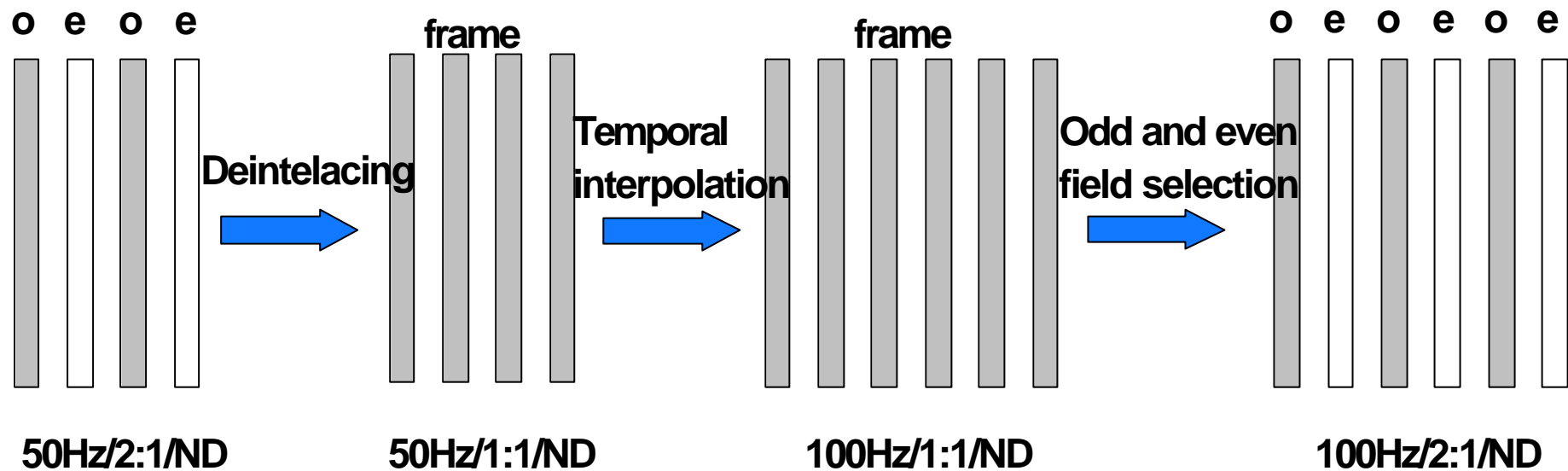


# Philips “Natural Motion” 100 Hz

- Only every fourth field in the output sequence is an original, all the others are interpolated to guarantee the parity changes.
- The fields marked with \*, such as B\*, contain the reconstructed missing lines instead of the original lines: being B an even field, B\* is an odd field.
- The intermediate fields are marked with two letters, as A\*B, to indicate that they are temporally interpolated using fields with the same parity.

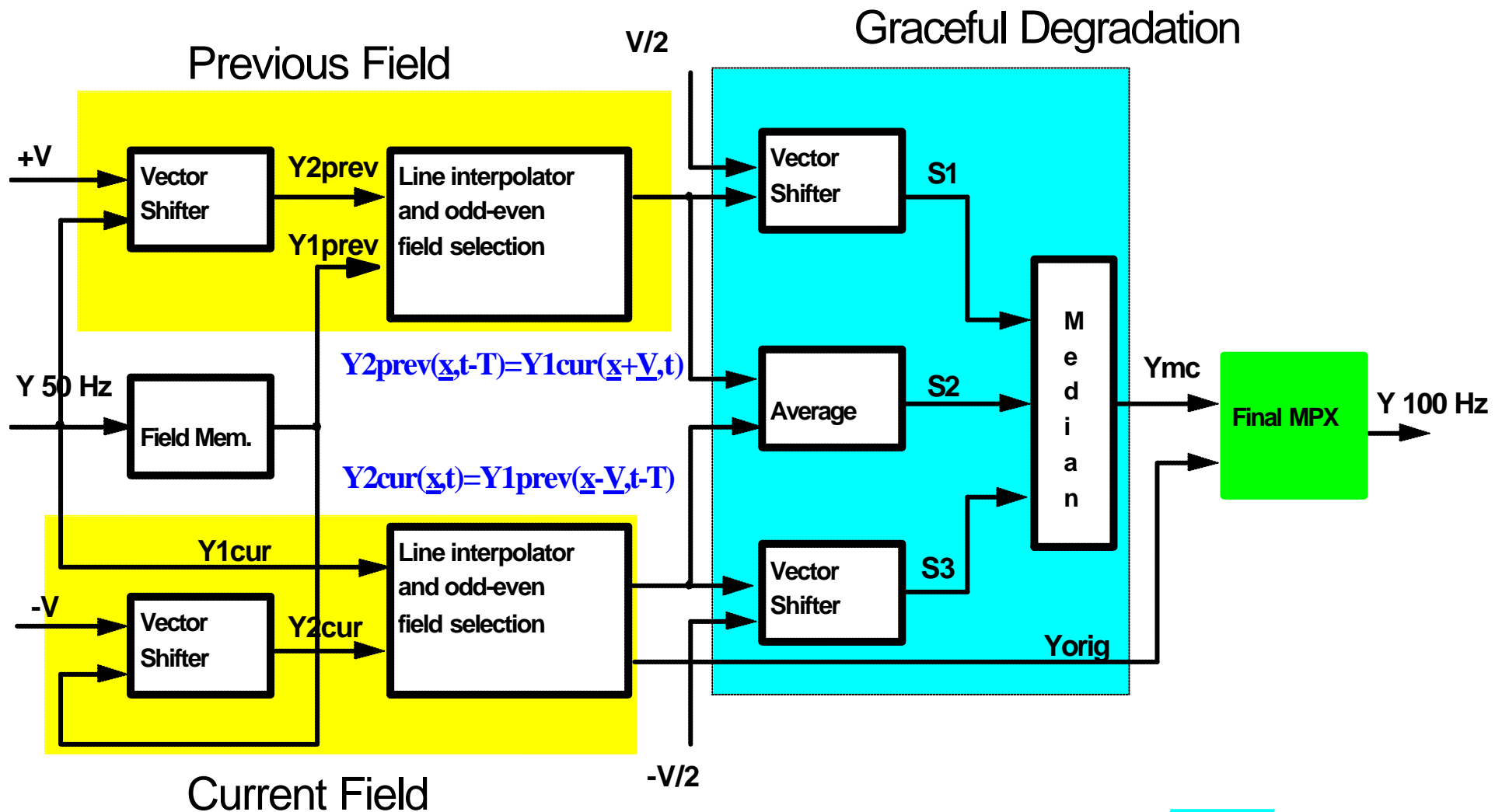


# 50 to 100 Hz multistage approach



**The de-interlacing process is applied contemporary to both fields, in order to get available all the lines of the two fields during the temporal interpolation computation.**

# Interpolation block diagram



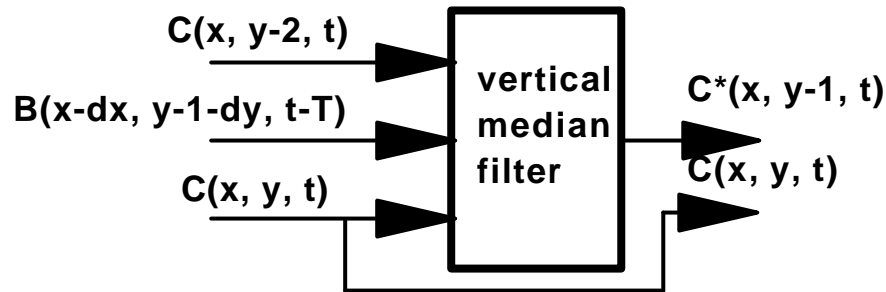
# Vertical/Temporal Median Filtering (1)

- Referring to the couple of fields **B** and **C**, a vector  $\underline{V}_{CB}=(d_x, d_y)$  is assigned to block  $(i, k)$  of  $C(\underline{x}, t)$ , if there is the best match with block  $(i+d_x, k+d_y)$  of  $B(\underline{x}, t-T)$ .
- De-interlacing process:
  - the missing lines  $C^*$  of the current field  $C(\underline{x}, t)$  are at first obtained with the motion compensation, that is,  $C^*(\underline{x}, t)=B(\underline{x} - \underline{V}_{CB}, t-T)$ .
  - The missing lines  $B^*$  of the previous delayed field should be computed as  $B^*(\underline{x}, t-T)=A(\underline{x} - \underline{V}_{BA}, t-2T)$ , if vectors  $\underline{V}_{BA}$  were properly stored in a field memory.

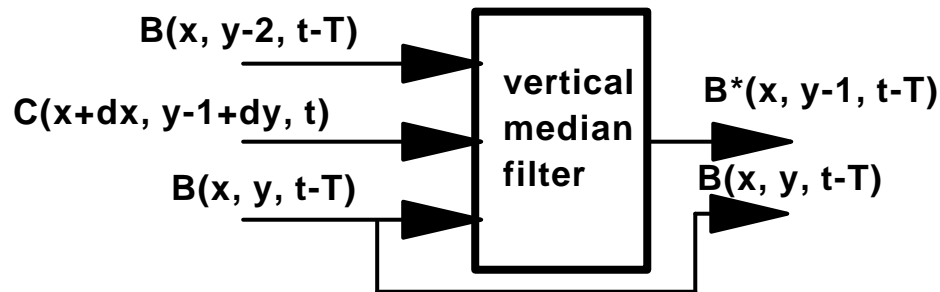
# Vertical/Temporal Median Filtering (2)

- However, field **A** is not available at the same time: it could be by using more than one field memory.
- This solution would require two field memories for the luminance to store **A** and **B**, when **C** is the current field.
- Approximation to de-interlace field **B** in order to minimize the number of field memories:
  - $B^*(\underline{x}, t-T) = C(\underline{x} + \underline{V}_{CB}, t)$
- The approximation is legitimate because of the high coherence of MV computed by a recursive search (true) Motion Estimation approach.

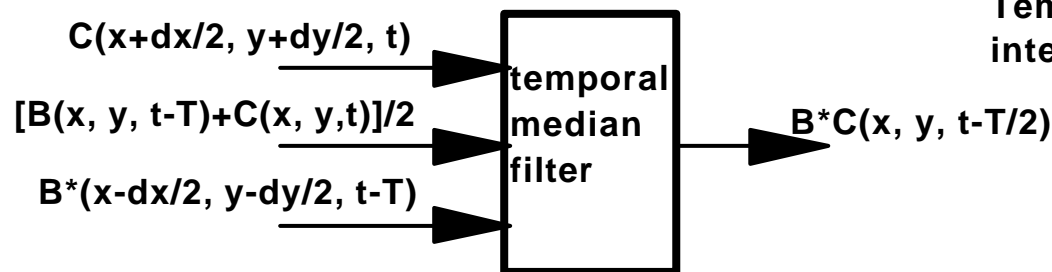
# Vertical/Temporal Median Filtering (3)



Progressive current frame demultiplexed in original C lines and reconstructed  $C^*$  lines.



Progressive previous frame demultiplexed in original B lines and reconstructed  $B^*$  lines.



Temporal interpolation of the intermediate  $B^*C$  field

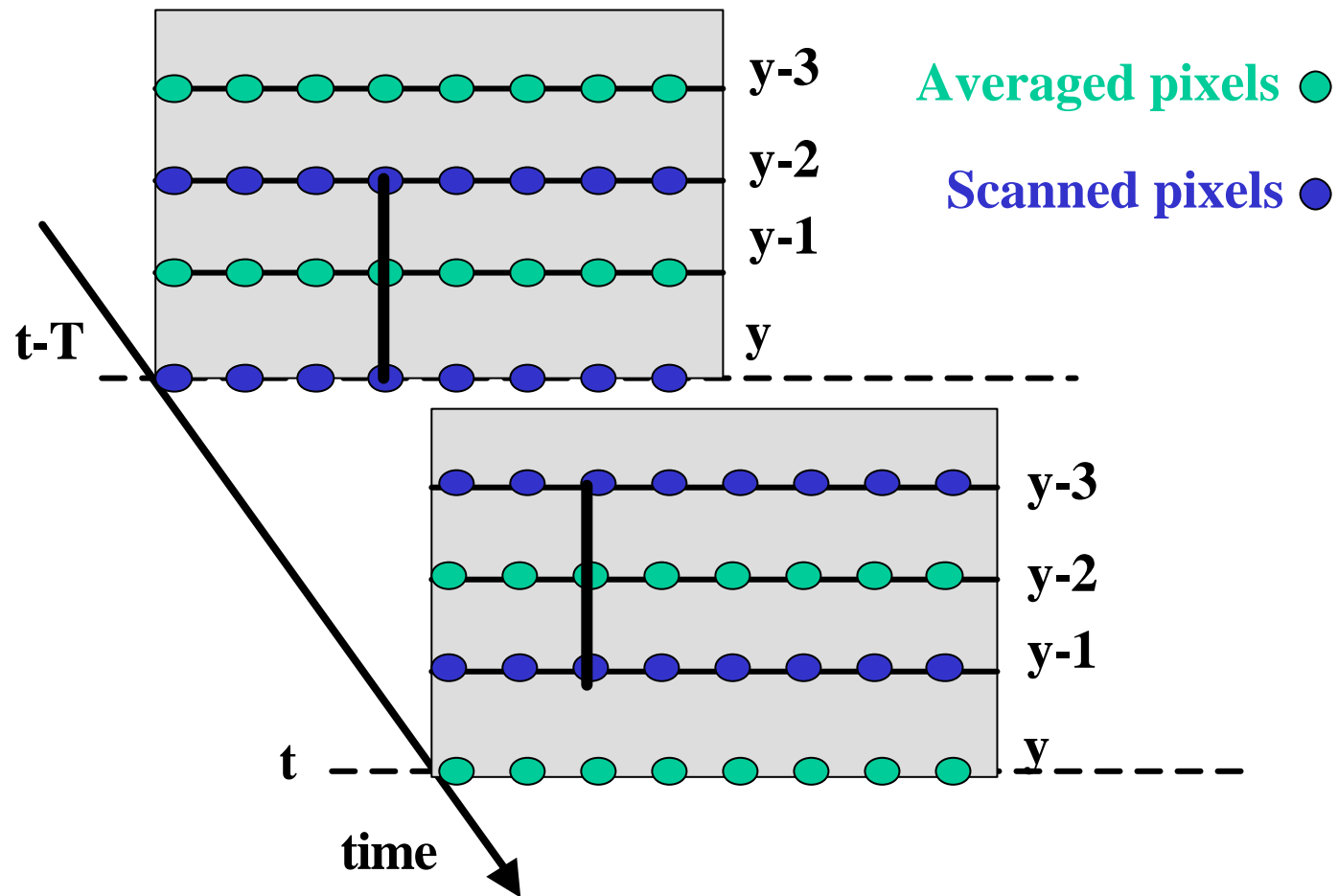
$$\underline{V}_{CB} = (dx, dy)$$



# De-interlacing or Line Rate Doubling

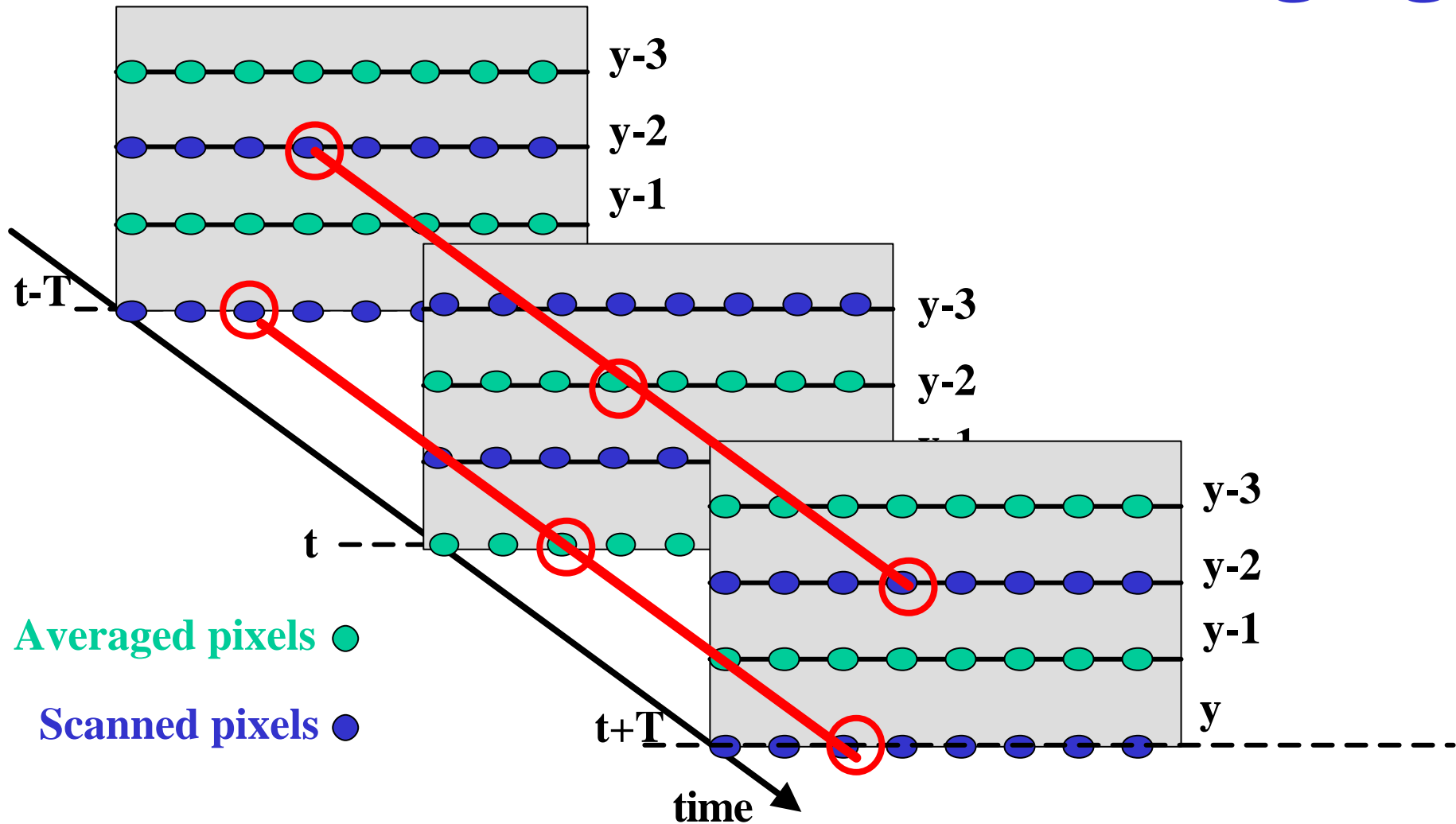
- The interlace technique is as a form of bandwidth reduction that was introduced in the early days of TV not to save channel capacity, but merely to lower the operating frequencies in the equipment.
- FRD on interlaced video signals requires the indispensable operation of Line Rate Doubling.
- We assume to have pictures with **lines** that are already time **compressed (ILC)**, through a line memory device (FIFO), with  **$T_L$**  period of a time-compressed line.

# LRD: intra averaging



$$I_{out}(\underline{x}, t) = 1/2 [ I_{LC}(\underline{x}, t-T_L/2) + I_{LC}(\underline{x}, t+T_L/2) ]$$

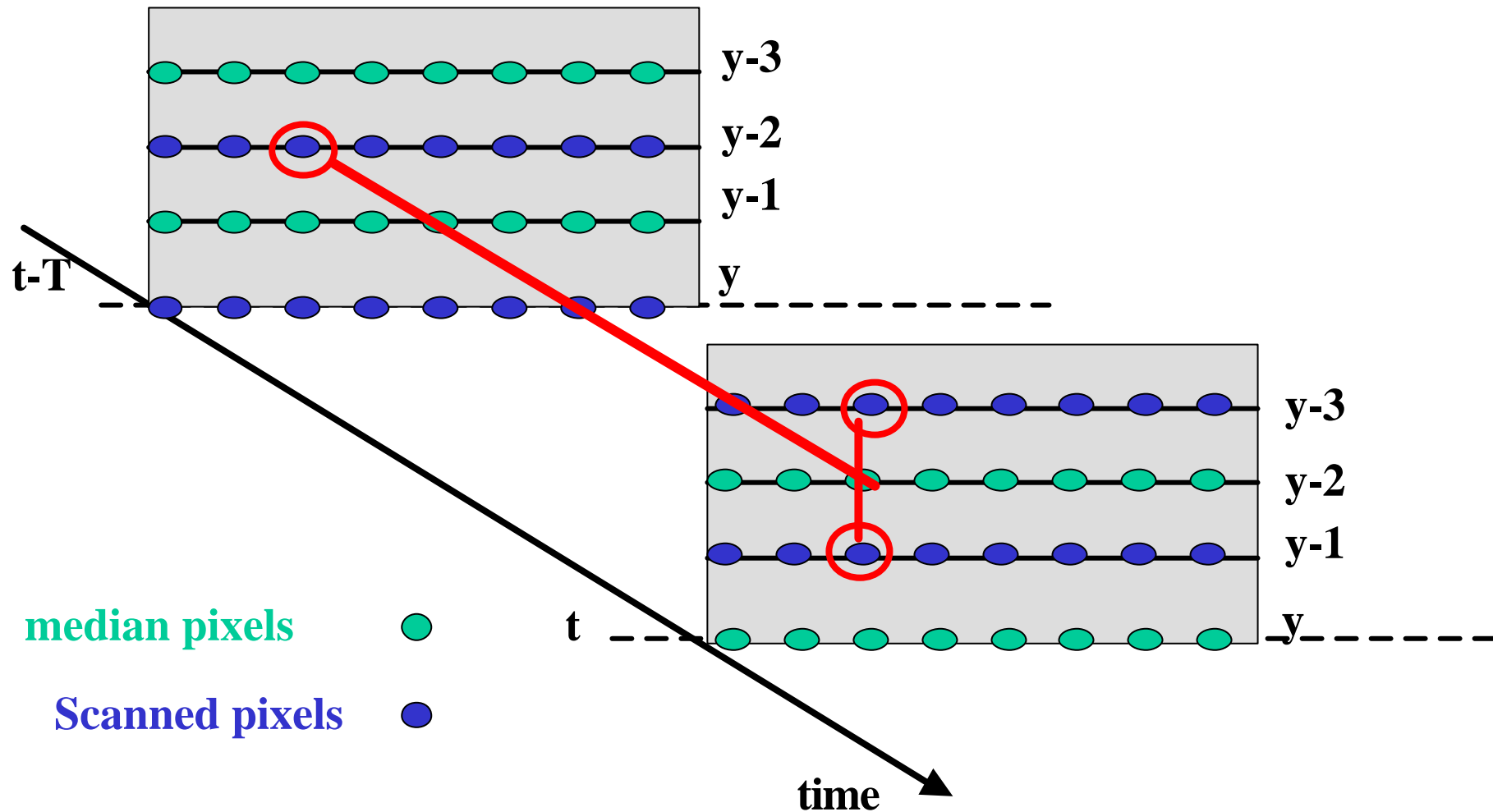
# LRD: inter averaging



$$I_{out}(\underline{x}, t) = 1/2 [ I_{LC}(\underline{x}, t-T) + I_{LC}(\underline{x}, t+T) ]$$



# LRD: median filtering

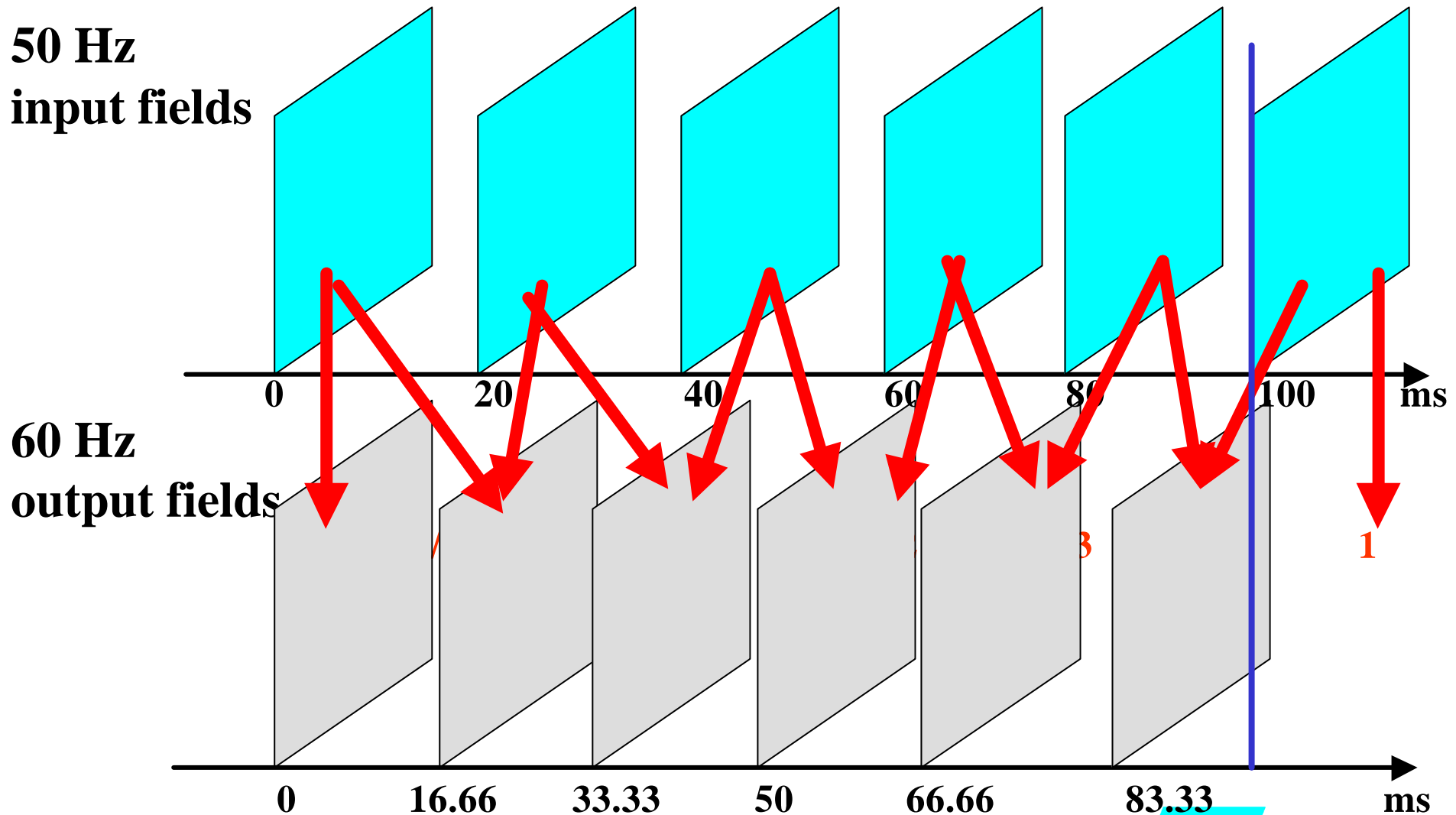


$$I_{out}(x, y-2, t) = \text{median}[ ILC(x, y-1, t), ILC(x, y-3, t), ILC(x, y-2, t-T) ]$$

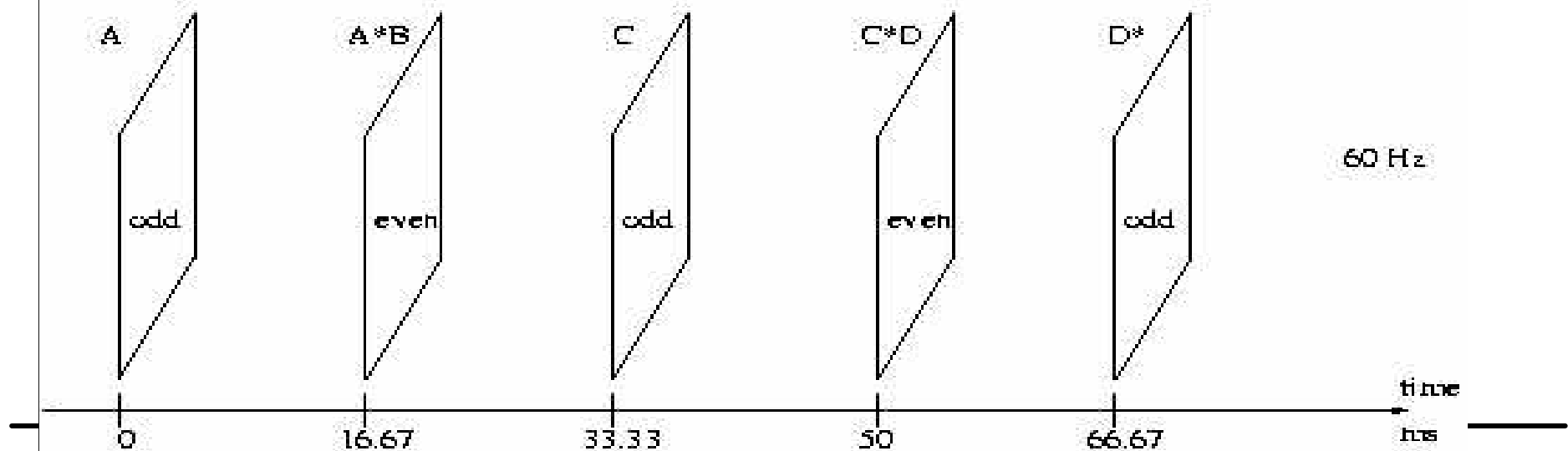
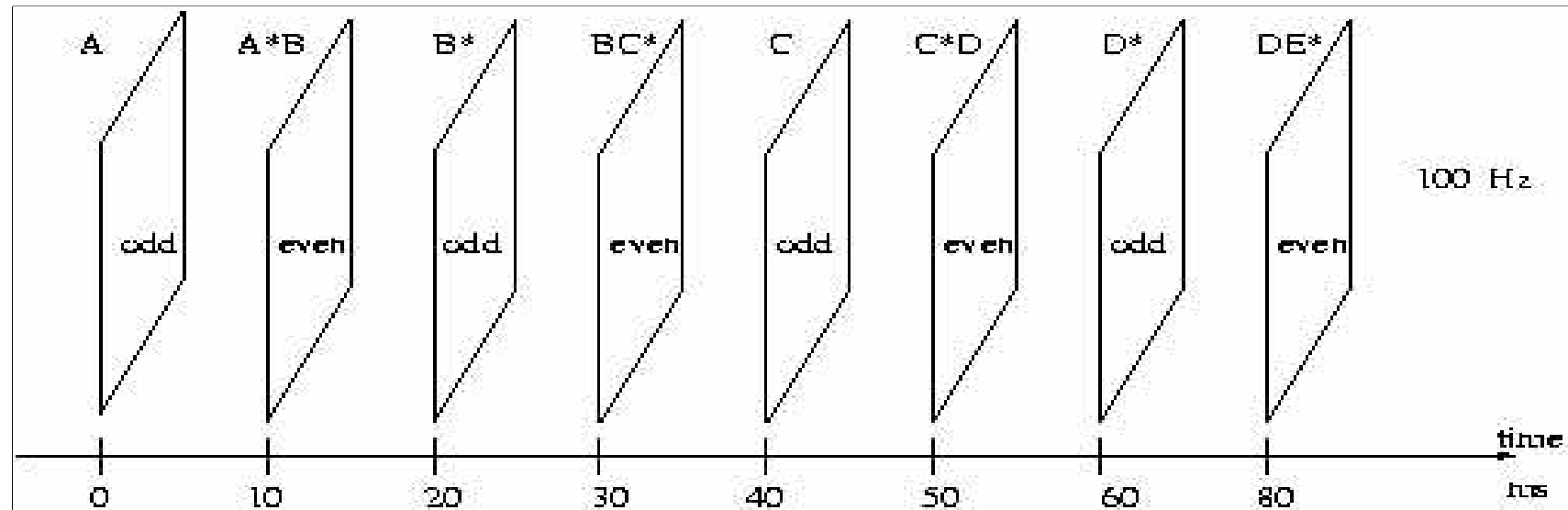
# LRD: summary

- **Intra-averaging:**
  - blur of vertical detail; no motion defects;
  - no elimination of line flicker and vertical alias;
- **Inter-averaging:**
  - good quality on stationary images;
  - blur and serration in moving parts of the picture
- **Median-filtering:**
  - good line flicker reduction in stationary image parts;
  - non linear filtering (imperfect reproduction of sinusoids).
- **Motion Compensation  $I_{out}(\underline{x}, t) = I_{LC}(\underline{x}-\underline{d}, t-T)$ :**
  - vertical alias cannot be removed completely in moving parts, unless the MV equals an odd integer number of frame lines.

# 50 Hz to 60 Hz conversion



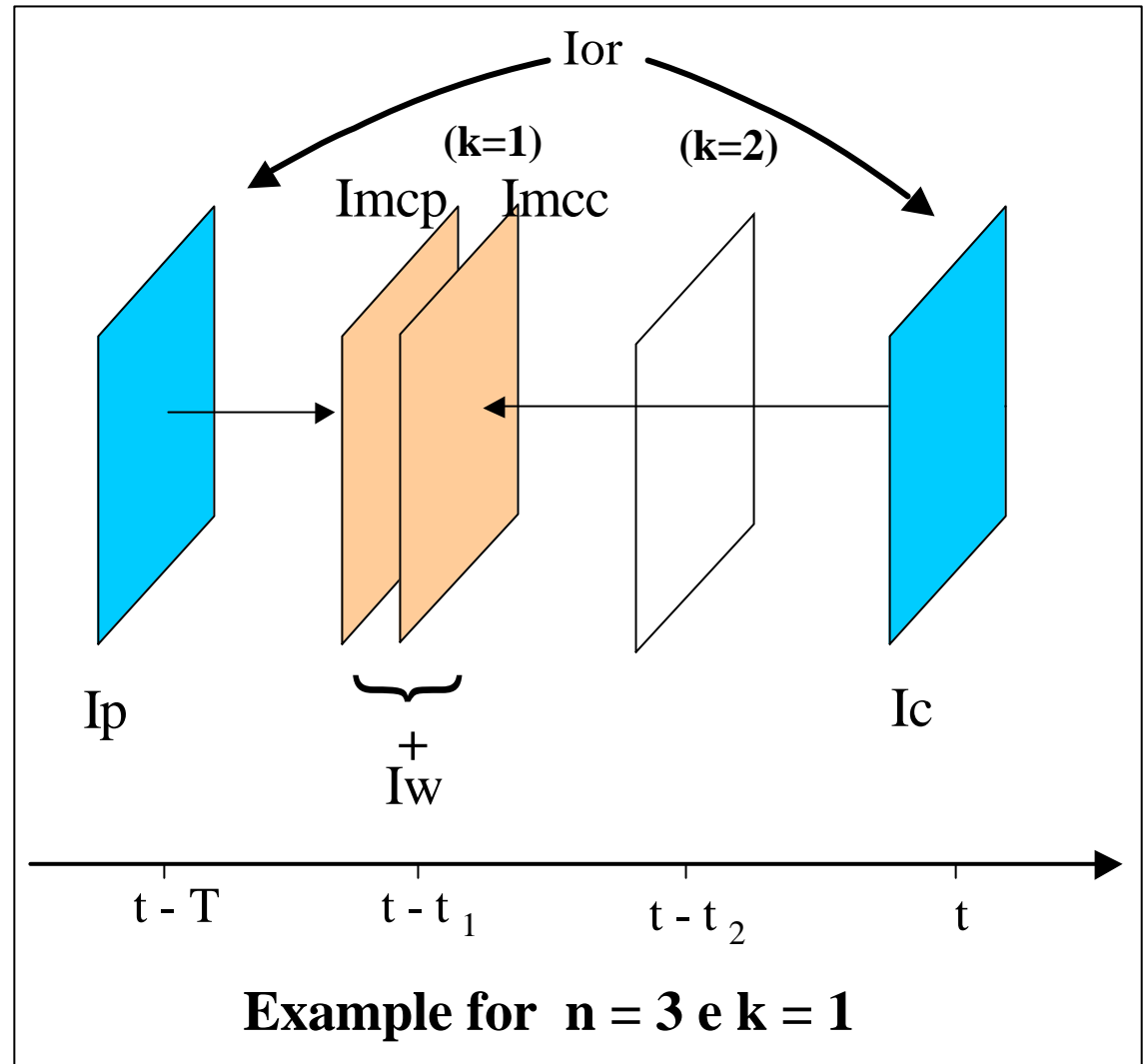
# 100 Hz to 60 Hz simple conversion



# H.263 temporal post-processing

$I_p$  = previous frame  
 $I_c$  = current frame  
 $I_{post}$  = output frame  
 $mc$  = motion compensated

n	K	$I_{mc}$
4	1	$I_{mcp}$
4	2	$I_{mcp}$
4	3	$I_{mcc}$
3	1	$I_{mcp}$
3	2	$I_{mcc}$
2	1	$I_{mcp}$



$$I_{post}(x,y,t-t_k) = \text{median}(I_{or}, I_{mc}, I_w)$$